

## Probability Review Topics

### 1D distributions

discrete (pmf) vs continuous (pdf)

normalized vs unnormalized

examples [1 2 1] ; uniform(0,1);  $1-x^2 \mid -1 \leq x \leq 1$ ;  $N(0,1)$

### 2D (bivariate) distributions

joint distribution (with examples of discrete and continuous)

examples [0 5 5; 10 0 0; 2 4 6];

[1 1 1; 1 1 1; 1 1 1];

[1 2 1; 2 4 2; 1 2 1];

bivariate Gaussian

marginal distributions

conditional distributions

independence

conditional independence

### Multivariate distributions

(vector of random variables  $X=[x_1 \ x_2 \ x_3 \ \dots \ x_n]$ )

### Cumulative Distribution Function (cdf)

[note: tie in with integral images!]

### Expectation / Expected Values

moments and central moments

mean, variance, covariance

"one-pass" computation of central moments

(useful for sequences / time series)

moments of binary images = shape descriptors

# Probability distribution functions

Let  $X = \{x_1, x_2, \dots, x_n\}$  discrete set  
 $f_X(x_i)$  is a pmf (prob mass function)

if  $f(x_i) \geq 0$   
 $\sum_{i=1}^n f(x_i) = 1$   
 $P(X=x_i) = f(x_i)$

Let  $X = \mathbb{R}$  continuous

$f_X(x)$  is a pdf (prob density function)

if  $f(x) \geq 0$   
 $\int_{-\infty}^{\infty} f(x) dx = 1$   
 $P(a \leq X \leq b) = \int_a^b f(x) dx$

note:  $P(X=x_i) = 0$  for continuous variables!

Important concept: normalized vs unnormalized

$f(x) \geq 0$

$\int_{-\infty}^{\infty} f(x) dx < \infty$

Can be treated as an unnormalized distribution

We can turn it into a pdf by dividing by appropriate normalizing constant  $C = \int_{-\infty}^{\infty} f(x) dx$

$P(x) = f(x) / \int_{-\infty}^{\infty} f(x)$

- after we learn distributions in unnormalized form (e.g. histograms)

~~some methods of inference do not need <sup>can use unnormalized</sup> distributions directly~~

- a lot of sound & fury in statistical estimation has to do with computing the normalizing constant for high-dimensional distributions

- however some methods of inference & sampling can use unnormalized distributions directly!

### Bivariate distribution

pmf  $f(x, y) = P(X=x, Y=y) = \text{Prob } X=x \text{ and } Y=y$

so-called Joint distribution  $\alpha$

pdf  $f(x, y)$ :  $P((x, y) \in A) = \iint_A f(x, y) dx dy$   
some region of  $\mathbb{R}^2$

running example pmfs

$$\begin{bmatrix} 0 & 5 & 5 \\ 10 & 0 & 0 \\ 2 & 4 & 6 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

### Marginal distributions.

Let  $f(x, y)$  be a joint distribution

or  $\int f(x, y) dy$

$$f_X(x) = P(X=x) = \sum_Y P(X=x, Y=y) = \sum_Y f(x, y)$$

similarly

$$f_Y(y) = P(Y=y) = \sum_X P(X=x, Y=y) = \sum_X f(x, y) \quad \text{---} \int f(x, y) dx$$

simplified notation (that helps to derive algebraic manipulations)

$$P(X) = \sum_Y P(X, Y) \quad P(Y) = \sum_X P(X, Y)$$

$\alpha$  Note: every meaningful statistical question can be answered (computed) from the joint distribution

## Conditional distribution

$$P(X|Y) = \frac{P(X, Y)}{P(Y)} = \frac{P(X, Y)}{\sum_x P(X, Y)}$$

also note:  $P(X, Y) = P(X|Y)P(Y) = P(Y|X)P(X)$   
example of factoring a joint distribution.

## Statistical Independence

r.v.'s  $x$  and  $y$  are independent if

$$P(X, Y) = P(X)P(Y)$$

note, in that case

$$P(X|Y) = \frac{P(X, Y)}{P(Y)} = \frac{P(X)P(Y)}{P(Y)} = P(X)$$

## Conditional Independence

a more subtle form of independence

$$P(X, Y|Z) = P(X|Z)P(Y|Z)$$

note: This does not imply nor is it implied by statistical independence

cdf (cumulative distribution function)

$$\begin{array}{l}
 P(X \leq x) \rightarrow \sum_{t=0}^x P(X=t) \quad \text{discrete } p \\
 P(X \leq x, Y \leq y) \rightarrow \int_{t=0}^x P(t) dt \quad \text{continuous } p
 \end{array}$$

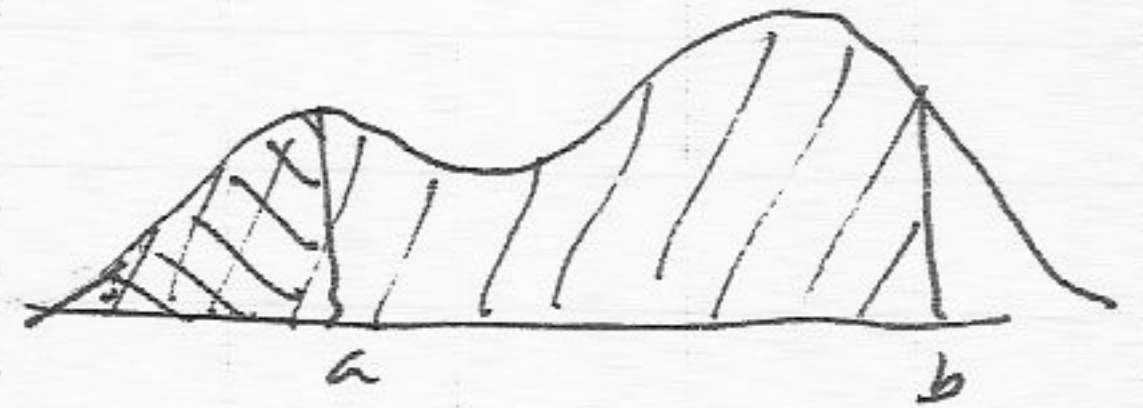
note: The cdf is a continuous function (defined over  $\mathbb{R}$ ) even for discrete probability distributions

example  $f_X(x) = \left[ \begin{array}{ccc} x=0 & x=1 & x=2 \\ 1/4 & 1/2 & 1/4 \end{array} \right]$

$$\text{cdf}(x) = F(x) = \begin{cases} 0 & x < 0 \\ 1/4 & 0 \leq x < 1 \\ 3/4 & 1 \leq x < 2 \\ 1 & x \geq 2 \end{cases}$$

note:

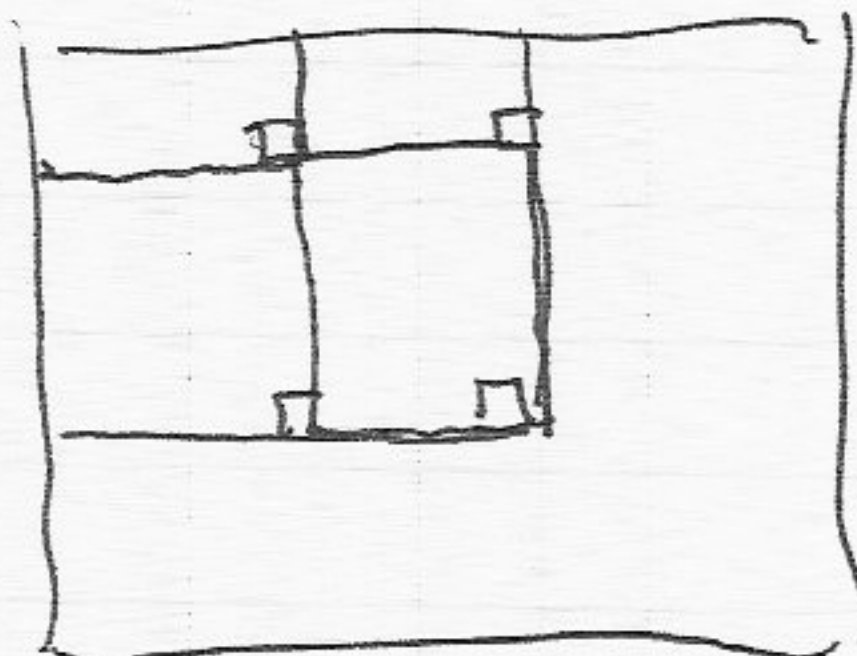
$$\begin{aligned}
 P(a \leq x \leq b) &= F(b) - F(a) \\
 &= P(X \leq b) - P(X \leq a)
 \end{aligned}$$



The in with integral images in vision

$$F(x, y) = P \sum_{x=1}^x \sum_{y=1}^y I(x, y)$$

$$P(x_2 \leq x \leq x_H, y_2 \leq y \leq y_H)$$



$$\begin{aligned}
 &F(x_H, y_H) - F(x_H, y_2) \\
 &- F(x_2, y_H) + F(x_2, y_2)
 \end{aligned}$$

Expected values

$$E_x(g(x)) = \int_{-\infty}^{\infty} g(x) f(x) dx \quad \leftarrow \text{expected value}$$

examples

"mean"  $E_x(x) = \int_{-\infty}^{\infty} x f(x) dx$  also known as 1st moment

discrete example of mean  $P(x) = \begin{matrix} x=0 & x=1 & x=2 \\ [1 & 2 & 3] \end{matrix} \times \frac{1}{6}$

$$E(x) = 0 \cdot \frac{1}{6} + 1 \cdot \frac{2}{6} + 2 \cdot \frac{3}{6} = \frac{1}{3} + 1 = \frac{4}{3}$$

Note that this is not a value (in this example) that can be taken by this discrete random variable!

mode of this example = argument of largest probability = 2  
it is the "most probable" value

~~2nd central moment~~ vs variance  
 $E(x^2)$  vs  $E((x-\mu)^2)$

$$E[(x-\mu)^2] = E[x^2 - 2\mu x + \mu^2] = E[x^2] - 2\mu E[x] + \mu^2 = E[x^2] - (E[x])^2$$

note: expectation is a linear operator!

a function of 1st & 2nd central moments

$$\text{cov}(x, y) = E_{xy}[(x-\mu_x)(y-\mu_y)]$$