

A Tuned Preconditioner for Inexact Inverse Iteration for Generalised Eigenvalue Problems

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Joint work with: Melina Freitag and Eero Vainikko

- 1 Motivation
- 2 Inexact Inverse Iteration
- 3 Costs in Krylov solvers
- 4 Tuning the right-hand side
- 5 Tuning and Preconditioning for a N-S problem

Inexact inverse
iteration and
tuned
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- $Ax = \lambda Mx$
- (λ_1, x_1) : $Ax_1 = \lambda_1 Mx_1$
- Large sparse nonsymmetric matrices
- Stability calculations for linearised N-S using Mixed FEM
- Hopf bifurcation: λ complex
- Simple eigenvalues
- Inverse Iteration with **iterative** solves for **shifted** linear systems
- Jacobi-Davidson, Arnoldi,...
- **TODAY**: costs of system solves

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1 Motivation

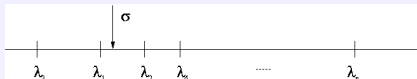
2 Inexact Inverse Iteration

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- $Ax = \lambda Mx, \quad (A - \sigma M)^{-1} Mx = \frac{1}{\lambda - \sigma} x$
- Fixed shift, $x^{(0)}, c^H x^{(0)} = 1$



for $i = 1$ to ... **do**

choose $\tau^{(i)}$

solve

$$\|(A - \sigma M)y^{(i)} - Mx^{(i)}\| \leq \tau^{(i)},$$

update eigenvector $x^{(i+1)} = \frac{y^{(i)}}{c^H y^{(i)}}$,

update eigenval $\lambda^{(i+1)} = \text{Ray Quot.}$

e-value residual $r^{(i+1)} = (A - \lambda^{(i+1)}M)x^{(i+1)}.$

end for

Consider

$$-\Delta u + 5u_x + 5u_y = \lambda x$$

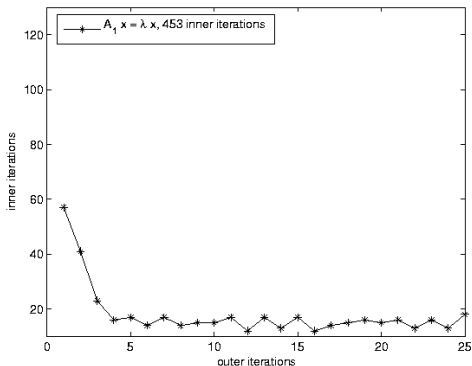
and its

- Finite Difference Discretisation: $A_1 x = \lambda x$
- Finite Element Discretisation: $A_2 x = \lambda M_2 x$

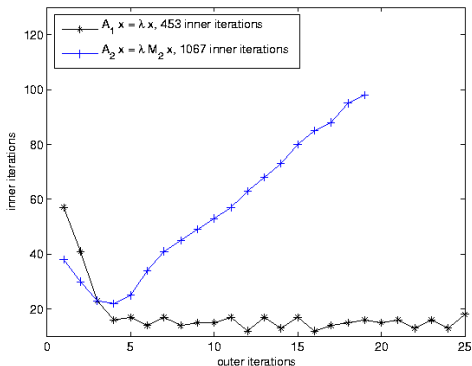
Apply inexact inverse iteration with fixed shift σ and decreasing tolerance:

$$(A_1 - \sigma I)y^{(i)} = x^{(i)}, \quad (A_2 - \sigma M_2)y^{(i)} = M_2 x^{(i)},$$

Inner v. outer iterations



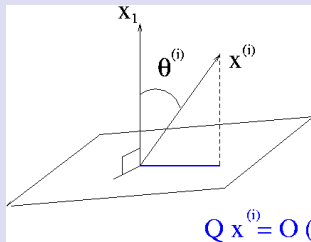
Inner v. outer iterations



For decreasing solve tolerances

- Since the linear systems are being solved more and more accurately, why isn't the # inner iterations increasing with i for $A_1x = \lambda x$?
- Why is the inner iteration behaviour different for the two discretizations?
- Can we achieve no increase in # inner iterations for $A_2x = \lambda M_2x$? (Yes: 'tuning')
- What implications are there for preconditioned iterative solvers?
- Next talk.....

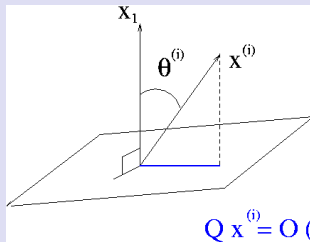
$Ax_1 = \lambda_1 x_1$, A symmetric (see Parlett's book)



$Q x^{(i)} = O(\sin \theta^{(i)})$ measure for the error

- $C|\sin \theta^{(i)}| \leq \|r^{(i)}\| \leq C'|\sin \theta^{(i)}|$, $r^{(i)} = (A - \lambda^{(i)}M)x^{(i)}$
- Nonsymmetric: $Ax = \lambda Mx$ [Golub/Ye (2000); Berns-Müller/Sp (2006)]
- If $\tau^{(i)} = C\|r^{(i)}\|$ then **LINEAR** convergence

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- $B = (A - \sigma I)$ and $b = x$
- (later $B = (A - \sigma M)$ and $b = Mx$)
- $\|b - By_k\| = \min \|p_k(B)b\| \leq C\rho^k \|b\|$, $(0 < \rho < 1)$.
- If $\|b - By_k\| \leq \tau$ then

$$k \geq C_1 + C_2 \log \frac{\|b\|}{\tau}$$

- Bound on k increases as τ decreases

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- for a **well-separated** eigenvalue
- For $B = (A - \sigma I)$ then $Bx_1 = (\lambda_1 - \sigma)x_1$



$$\|b - By_k\| = \min \|p_k(B)b\| \leq \|p_{k-1}(B)q_1(B)b\|$$



$$\|b - By_k\| \leq \|p_{k-1}(B)q_1(B)Qb\|$$

- to achieve $\|b - By_k\| \leq \tau$ then

$$k \geq C_3 + C_4 \log \frac{\|Qb\|}{\tau}$$

- Bound on k depends on $\frac{\|Qb\|}{\tau}$

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Some answers for $\tau^{(i)} = C\|r^{(i)}\| = \mathcal{O}(\sin \theta^{(i)})$

$$(A - \sigma I)y^{(i)} = x^{(i)}$$

- $b = x^{(i)}$ and $\|Qx^{(i)}\| = \mathcal{O}(\sin \theta^{(i)})$
- Hence $\|Qb\|/\tau = \mathcal{O}(1)$ and the bound on k doesn't increase
- Consistent with numerics for $A_1x = \lambda x$

$$(A - \sigma M)y^{(i)} = Mx^{(i)}$$

- $b = Mx^{(i)}$ and $\|QMx^{(i)}\| = \mathcal{O}(1)$
- Hence $\|Qb\|/\tau = \mathcal{O}(\sin \theta^{(i)})^{-1}$ and the bound on k increases
- Consistent with numerics for $A_2x = \lambda M_2x$

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For $(A - \sigma M)y^{(i)} = Mx^{(i)}$

Introduce the “tuning matrix” \mathbb{T} and consider (think preconditioning)

$$\mathbb{T}^{-1}(A - \sigma M)y^{(i)} = \mathbb{T}^{-1}Mx^{(i)}$$

- Key Condition: $\mathbb{T}^{-1}Mx^{(i)} = x^{(i)}$

- Re-arrange to:

$$Mx^{(i)} = \mathbb{T}x^{(i)}$$

- Implement by rank-one change to Identity:

$$\mathbb{T} := I + (Mx^{(i)} - x^{(i)})c^H \quad (c^H x^{(i)} = 1)$$

- Use Sherman-Morrison to get action of \mathbb{T}^{-1}

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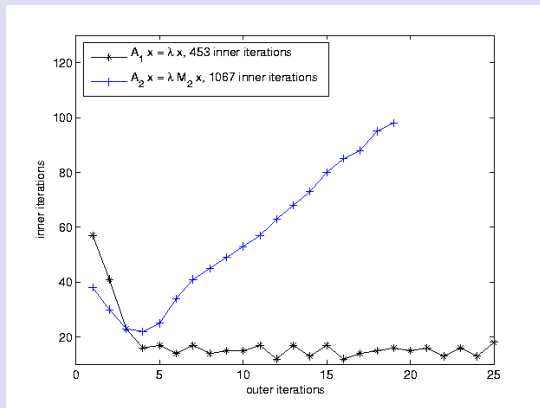
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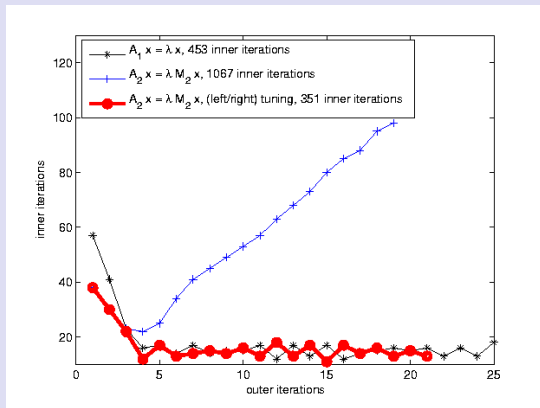
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Flow past a circular cylinder (incompressible Navier-Stokes)

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- $Re = 25, \lambda \approx \pm 10i$
- Mixed FEM: $Q_2 - Q_1$ elements
- Elman preconditioner: 2-level additive Schwarz
- ≈ 54000 degrees of freedom

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Figure: Fixed Shift

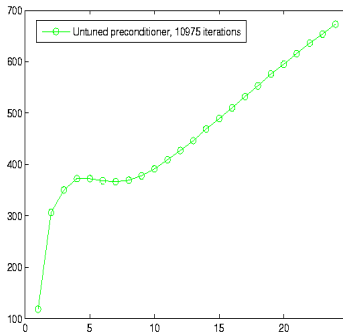
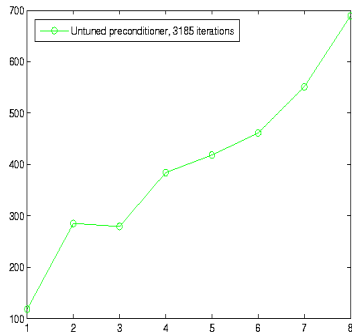


Figure: Rayleigh Quotient Shift



- Preconditioned iterates should behave as in unpreconditioned standard EVP case
- right preconditioned system $(A - \sigma M)P_S^{-1}\tilde{y}^{(i)} = Mx^{(i)}$
- theory of Krylov solver for $By = b$ indicates that $Mx^{(i)}$ should be close to eigenvector of $(A - \sigma M)P_S^{-1}$
- Introduce a tuned preconditioner \mathbb{P} so that we solve

$$(A - \sigma M)\mathbb{P}^{-1}\tilde{y}^{(i)} = Mx^{(i)}$$

- Remember $Ax_1 = \lambda_1 Mx_1$, so condition $\mathbb{P}x^{(i)} \approx \lambda^{(i)} Mx^{(i)}$?
- Take

$$\mathbb{P}x^{(i)} = Ax^{(i)}$$

since then

$$\mathbb{P}x^{(i)} = \lambda^{(i)} Mx^{(i)} + (Ax^{(i)} - \lambda^{(i)} Mx^{(i)})$$

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Implementation of $\mathbb{P}x^{(i)} = Ax^{(i)}$

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- Given P_S
- Evaluate $u^{(i)} = Ax^{(i)} - P_Sx^{(i)}$

- Rank-one update:

$$\mathbb{P} = P_S + u^{(i)}c^H$$

$$\mathbb{P}x^{(i)} = P_Sx^{(i)} + u^{(i)}c^Hx^{(i)} = P_Sx^{(i)} + u^{(i)} = Ax^{(i)}$$

- Use Sherman-Morrison - one extra backsolve per outer iteration

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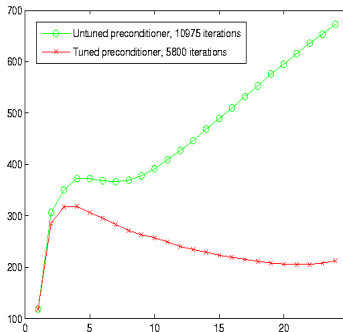
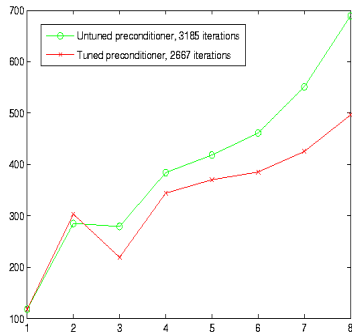


Figure: Rayleigh Quotient Shift



- When preconditioning an eigenvalue problem think of adding the property

$$\mathbb{P}x^{(i)} = Ax^{(i)}$$

to your favourite preconditioner

- This can be achieved by a simple and cheap rank one modification



M. A. FREITAG AND A. SPENCE, *Convergence rates for inexact inverse iteration with application to preconditioned iterative solves*, 2006.

Submitted to BIT.



——, *A tuned preconditioner for inexact inverse iteration applied to Hermitian eigenvalue problems*, 2006.

Submitted to IMA J. Numer. Anal.